Introduction to Arduino

Maker Workshop

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By the end of this class, you'll:

- Know how to create programs for Arduino and run them.
- Have learned about digital input and output, reading switches and lighting LEDs
- Have created a *Whack-a-Mole* type game.
- Be prepared to follow Arduino tutorials online and continue exploring.

Enabling Exploration, Creativity, and Excellence In Art+Make+Tech

Challenging and embracing ideas related to new technologies and social platforms through the education, entertainment and engagement of our membership and the community-at-large.

- 121Studios: Coworking for Creatives
- Unlab: Hackerspace
- Events: STEAM Outreach & Edu., ExplodeConf, Nuit Blanche

Freelance Embedded Systems Engineer

- Indoor location tracking w/ Bluetooth
- Keychain / Fitness Band Widgets
- Joystick for VR
- Remote Controls
- Internet of S*#t

Shawn: The Fun Stuff

Hacker, Church of the Weird Machine, Odd Duck

- Arduino compatible implant
- EEG Games / Toy Hacking
- Brain Stimulation
- Be Weird, Make Weird, Have Fun!





Mechanical Engineer

- Working in the medical device industry
- Experience in medical device R&D and Manufacturing
- Teaching SolidWorks CAD at Fanshawe

Raphael: The Fun Stuff

Thinker, Jack of all Trades - Master of None

- Arduino for Fun, and Odd Jobs
- 3D Printer Hobbyist
- PC Builder & Gamer
- Fish keeper





What's in your kit?

- Arduino Uno R3
- Solderless Breadboard
- Connecting wires
- LEDs
- Resistors, Potentiometer
- Buzzer

$\mu \mathrm{C}$ + reset button + led + USB

It's a kit (on a board) with the bare minimum components to easily use the μ C hardware. They do the basic, boring design needed for any board, so users only need to add the neat stuff.

The Arduino folks also adapted an *Integrated Development Environment* (IDE) to their boards. This IDE allows us to easily write programs for their boards and then write the programs to the μ C.

Get the Arduino IDE:

https://www.arduino.cc/en/Main/Software

Circuit Basics

Current is the flow of charge through a circuit. Measured in Amperes (A).

Circuits have a resistance to current flow that depends on the parts in the circuit.

Measured in Ohms (Ω)

Voltage is a potential (akin to a pressure) pushing the current through a circuit. Current is said to flow from higher (+) voltage to lower (-) voltage.

Measured in Volts (V)

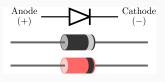
Voltage, Current and Resistance are related to each other.

- As voltage increases, current increases
- As voltage decreases, current decreases
- As resistance increases, current decreases
- As resistance decreases, current increases

If charge were water, then:

- resistance = obstacles blocking flow
- current = flow rate
- voltage = change in height *or* pressure.

- One way value for current¹
- LED \equiv Light Emitting Diode
- Band marks (-)²
- Longer leg marks (+)





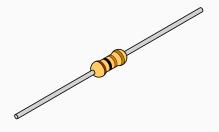
¹https://learn.sparkfun.com/tutorials/diodes

²https://learn.sparkfun.com/tutorials/polarity/diode-and-led-polarity

- Diodes don't limit current
- Diodes aren't perfect (some current turned to heat)
- Too much current \rightarrow Too much heat \rightarrow

What's that smell?

- Resists/limits the flow of current
- Needed for LEDs: $\approx 1000\,\Omega$
- Button Pull-up/down: $\geq 10 \, k\Omega$
- Color coded, Google it



- Buttons connect or disconnect two wires/parts
- Momentary Switch: Normally Closed (NC), Normally Open (NO)
- Toggle Switch

A circuit is a completed loop from HIGH potential (voltage) to LOW, which causes current to flow through some other components along the way.

Often these *other* components are *transducers*, which convert electrical energy into another sort of energy:

Speaker	$Electrical \to Sound$
Microphone	$Sound \to Electrical$
LED	$Electrical \to Light$
LED	$Light \to Electrical$
Piezoelectric	$Electrical \to Motion$

The power supply provides the energy to drive the system. Can be a:

- Voltage Regulator (converts one potential to another)
- Batteries
- Solar Panel

In our circuits, your laptop is converting it's power source to $5\,V$ and delivering power to our circuit via USB.

μ Controller

Microcontroller (μ C) is a *processor*, *memory* and a few *peripherals* on a standalone chip.

Processor is a group of transistors that understands a dozen or so commands (ADD, SUB, JUMP..)

Memory a circuit that can hold values.

Peripherals Vary chip to chip, but often include timers, communications and ADC, DAC.

Seems complicated, but really simple. They read a command from the start of memory, then execute the command. At the end of the command, read the next command from the next memory cell and repeat¹

¹some commands change the address of the next fetched command

- Vcc: The power supply of the circuit elements
- GND: The reference voltage (usually 0 V)
- Connecting a part to Vcc = Logical 1 or High
- Connecting to GND = Logical 0 or Low
- Connecting various pins to Vcc or Ground is all the $\mu{\rm C}$ can do to talk to the world 2

 $^{^{2}}w/o$ fancy peripherals or dirty tricks

Most of the pins on the Arduino can be set for INPUT or OUTPUT mode.

- INPUT mode pins listen for a signal (0 or 1) from another device
- OUTPUT mode pins drive the pin High or Low

What's happens if an INPUT mode pin tries to read the value of a pin that is connected to nothing? Is that a 1 or 0?

No one knows!

It's dependant of transient charges, static, nearby electric fields, the phase of the moon, ... Whenever you want to check a digital signal, make sure that something is *driving* it (ensuring Vcc or GND).

If one end of an LED is connected to ground, and the other end is connected to an OUTPUT pin on a μ Controller, then:

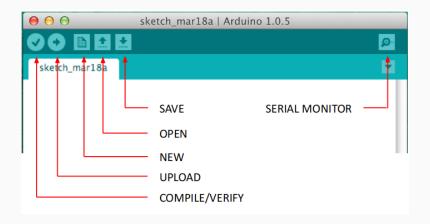
- If the μ C sets the pin High (Vcc, 5 V) then current will flow from the pin through the LED and turn it on.
- If µC sets the pin Low (GND, 0V) then the current will not flow and the LED is off.

Let's start programming

Configure Arduino

<u>T</u> ools <u>H</u> elp		
Auto Format	Ctrl+T	
Archive Sketch		
Fix Encoding & Reload		
Serial Monitor	Ctrl+Shift+M	
Serial Plotter	Ctrl+Shift+L	of the potentiometer
Board: "Arduino/Genuino Uno"	•	Boards Manager
Port	►	Arduino AVR Boards
Programmer: "AVRISP mkII"	•	🔿 Arduino Yún
Burn Bootloader		💿 Arduino/Genuino Uno
		🔿 Arduino Duemilanove or Diecimila
		🔿 Arduino Nano
		🔿 Arduino/Genuino Mega or Mega 2560
		🔿 Arduino Mega ADK
		∩ Arduino Leonardo

- Board: Arduino/Genuino UNO
- Port: ...



#define LED 13

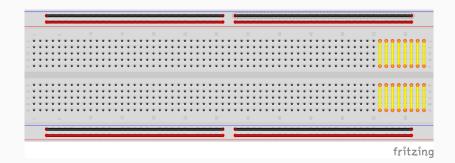
```
/* the setup function runs once on reset / power */
void setup() {
   pinMode(LED, OUTPUT);
}
```

```
/* loop() repeats until reset or power off */
void loop() {
    digitalWrite(LED, HIGH); // turn on LED
    delay(1000); // wait for a second
    digitalWrite(LED, LOW); // turn the off LED
    delay(1000);
```

```
}
```

Add Some Parts

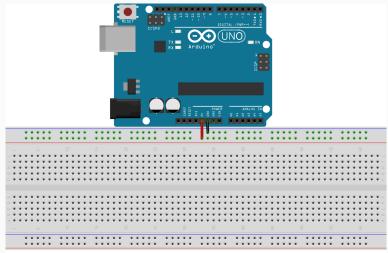
Breadboard



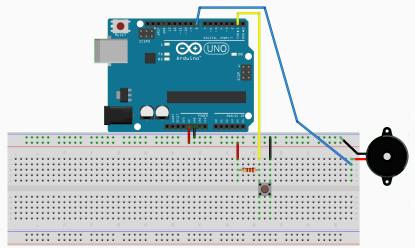
- Connectors gently pinch component leads, wires.
- Have internal connections

Power Up the Rails

We use the long rows to distribute power. The Arduino outputs 5 V on the pin marked 5V, the reference (GND) is marked GND.

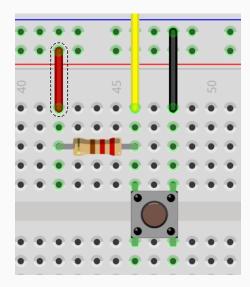


Buzzer & Button: Hardware





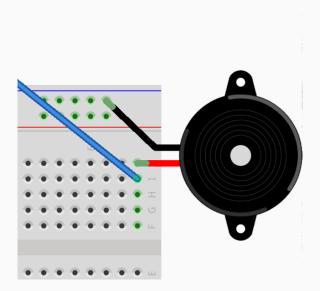
Push Button: Zoom



Reading a floating pin is **bad**. A switch only connects and disconnects a wire. When the wire is disconnected... the INPUT pin is floating!

Solution:

Connect the pin to Vcc so that it reads High; use a resistor to prevent short circuit (limit current).



```
#define BUTTON 2
#define BUZZER 8
```

```
int button_state;
```

```
void setup() {
   pinMode(BUTTON, INPUT);
   pinMode(BUZZER, OUTPUT);
   digitalWrite(BUZZER, LOW); /* Start w/ LED off */
}
```

Declare a variable:

int button_state = HIGH;

<type> <name> [= <initial value>]; (value optional)

It's a name, like a preprocessor #define, but the value can change at *runtime*

```
if (condition) {
    // body: Runs if condition true ( != 0)
} else {
    // Runs if condition false ( == 0 )
}
```

- body code inside curly braces: { }
- condition evaluates to 0 \rightarrow body code skipped
- else section is optional, runs if condition evaluates to 0
- condition evaluates to not 0 \rightarrow body code runs

In C-like languages, the == operator checks if two things (statements, variables, ...) are equal to each other.

- It returns 1 if the items are equal, or
- It returns 0 if the items are not equal

Functions make it easy to reuse code. You already know / use several functions:

- pinMode
- digitalWrite
- delay

digitalRead(pin number) returns HIGH or LOW depending on current state of any **INPUT** pin.

You can write your own functions!

```
void my_function(int arg1, ...) {
    // Do fun things
}
```

void: Return type. Void means nothing returned. Can be any type.
my_function: A name for your function
arguments: A type and name for any parameters you want to use in your function from the outside.

Define a function once, you can use it again and again. Better than copy/pasting.

```
void buzz(int ms) {
    digitalWrite(BUZZER, HIGH);
    delay(ms);
    digitalWrite(BUZZER, LOW);
}
void loop() {
  button_state = digitalRead(BUTTON);
  if (button state == LOW) {
    buzz(100);
  }
}
```

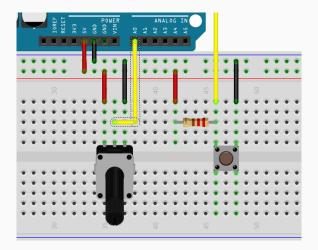
More Parts

Puh - ten - she - ometer

- Pot for short
- A Voltage Divider
- Voltage at *Wiper* is somewhere between potential at the two terminals.
- The exact wiper potential depends on the position of the knob/lever.

- A peripheral of the *µ*Controller
- Measures Potential, outputs a number
- In our case, $0\,V \rightarrow 0$ and $5\,V \rightarrow 1023$
- A0-A5 pins on Arduino can be used
- Fun uses: Reading pot position, sampling audio, reading from sensors

The Pot Hookup



Connect center pin to A0, outer pins to (+) and (-) rails

Pot Code

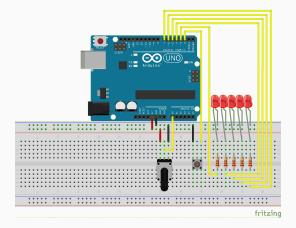
analogRead(*pin*) returns the voltage at the pin (0-1023), it can be used directly or via variable.

```
#define LED 13
void setup() {
  pinMode(LED, OUTPUT);
}
void loop() {
  digitalWrite(LED, HIGH);
  delay(analogRead(A0));
  digitalWrite(LED, LOW);
  delay(analogRead(A0));
}
```

Since the delay() calls use the result of analogRead (0-1023), the blink rate changes with knob position.

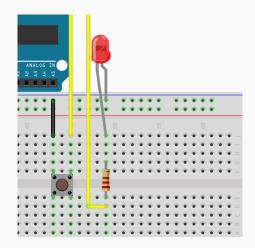
Shall we play a game?

Hooking up a bunch of LEDs



LEDs, the first one

Looks complicated, but for each LED: The short leg goes to ground, the long leg goes to one end of a resistor, and the other end of the resistor goes to the arduino pin.



for (initializer ; condition; increment) {
 // This body will repeat while condition != 0
}

initializer Executed once at beginning of loop. Often used to declare a local variable.
condition Loop will repeat while condition is true (≠ 0)
increment Runs after each loop. Often used to increment

variables.

All fields are optional

```
setup() {
    pinMode(3, OUTPUT);
    pinMode(4, OUTPUT);
    pinMode(5, OUTPUT);
    pinMode(6, OUTPUT);
    pinMode(7, OUTPUT);
}
```

Cylon Simulator: Part. 2

```
loop () {
    for (int i = 4; i <= 7; i++) {</pre>
        delay ms = analogRead(A0);
        digitalWrite(i - 1, LOW);
        digitalWrite(i, HIGH);
        delay(delay ms);
    }
    for (int i = 6; i >= 3; i--) {
        delay_ms = analogRead(A0);
        digitalWrite(i + 1, LOW);
        digitalWrite(i, HIGH);
        delay(delay ms);
    }
```

}

```
while ( statement ) {
    // This body will repeat while condition is true
    // True means statement != 0
}
```

initializer Executed once at beginning of loop. Often used to declare a local variable.
 condition Loop will repeat while condition is true (≠ 0)
 increment Runs after each loop. Often used to increment variables.

All fields are optional

```
#define WINNER 5
void check delay(int cur led, int delay ms) {
  unsigned long start = millis();
  while (millis() < start+delay_ms) {</pre>
    if (digitalRead(BUTTON) == LOW) {
      if (cur led == WINNER) {
        do winner();
      } else {
        while (digitalRead(BUTTON) == LOW) {
          do loser();
        }
      }
    }
  7
```

```
void set_all_leds(int state) {
  for (int i = 3; i <= 7; i++) {
    digitalWrite(i, state);
  }
}
void do_loser(void) {
  buzz(500);
}</pre>
```

```
void do_winner(void) {
   set_all_leds(HIGH);
   buzz(100);
   delay(100);
   buzz(100);
   set_all_leds(LOW);
}
```

Putting it Together

```
loop () {
    for (int i = 4; i <= 7; i++) {</pre>
        delay_ms = analogRead(A0);
        digitalWrite(i - 1, LOW);
        digitalWrite(i, HIGH);
        check delay(i, delay ms);
    }
    for (int i = 6; i >= 3; i--) {
         . . .
        check_delay(i, delay_ms);
    }
}
```

The End?

Extra Credit

Ohm's Law relates current to potential and resistance.

$$V = IR$$
$$I = \frac{V}{R}$$
$$R = \frac{V}{I}$$

- V = Potential in Volts (V)
- I = Current in Amperes (A)
- R = Resistance in Ohms (Ω)

The datasheet for an LED says that the maximum continuous current is 15 mA. Your circuit operates at 5 V^1 . How big should your resistor be?

$$\Omega = \frac{5 \,\mathrm{V}}{0.015 \,\mathrm{A}} = 333.\overline{3}\Omega$$

How much current for our cheet sheet value?

$$\mathsf{A} = \frac{5\,\mathsf{V}}{1\,\mathsf{k}\Omega} = 5\,\mathsf{m}\mathsf{A}$$

 $^{^{1}}$ Actually, this calculation is inaccurate. LEDs will have a *forward voltage drop* of between 1.8V and 3.3V this should be subtracted from V above... but it's not critical.

- No single pin should source more that 20 mA (40 mA is absolute max)
- Pins are ganged together in groups of 8, no group should source more than 150 mA total
- The whole board cannot source more than 200 mA total

Practically speaking, this means that the Arduino cannot drive speakers, most motors, or anything normally mains powered.

You can control almost anything with an arduino, you just can't power it with the Arduino. There are various devices that let you switch highier powered devices:

- Transistors
- Relays
- Solid State Relays
- Triac

Many different logic levels are in common use: 1.2 V, 1.8 V, 2.5 V, 3.3 V, and 5 V. The voltage cited is the *nominal* Vcc of the system. A HIGH signal is generally any voltage $\geq \frac{2}{3}V_{cc}$. A LOW signal is generally any voltage $\leq \frac{1}{3}V_{cc}$. In your travels, you're likely to see both 5 V and 3.3 V sensors and peripherals.

Since $3.3 \text{ V} \ge \frac{2}{3} V_c c$ your Arduino will accept input from a 3.3 V peripheral without issue.

If you drive an output to 5 V while it's connected to a 3.3 V peripheral with an Arduino **it will blow up your peripheral**.³

 $^{^3}$ In the datasheet for the sensor, it'll have a section called Absolute Maximums. Generally 3.3 V parts won't accept more that \approx 3.6 V, but some will.

Solutions:

- Level Shifter: A dedicated chip that translates between voltages. Available as uni or bidirectional.
- Buy a 3.3V Arduino Compatible. Arduinos are available that operate at the lower voltage.