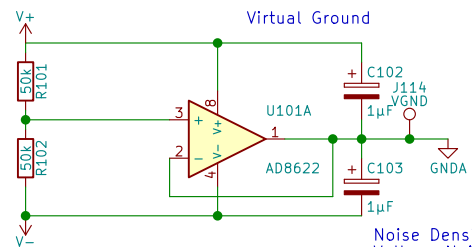
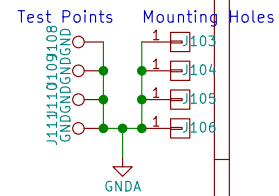
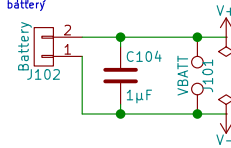
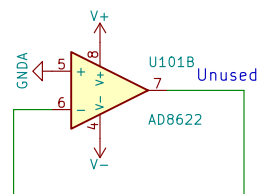


Excitation Supply  
Now directly from battery



Noise Density: 12nV/√Hz  
Voltage Noise (0.1-10Hz): 0.2uV p-p  
Offset: <125uV  
Drift: <1.2uV/°C



Notes:

R101,R102: Resistor pack for good match

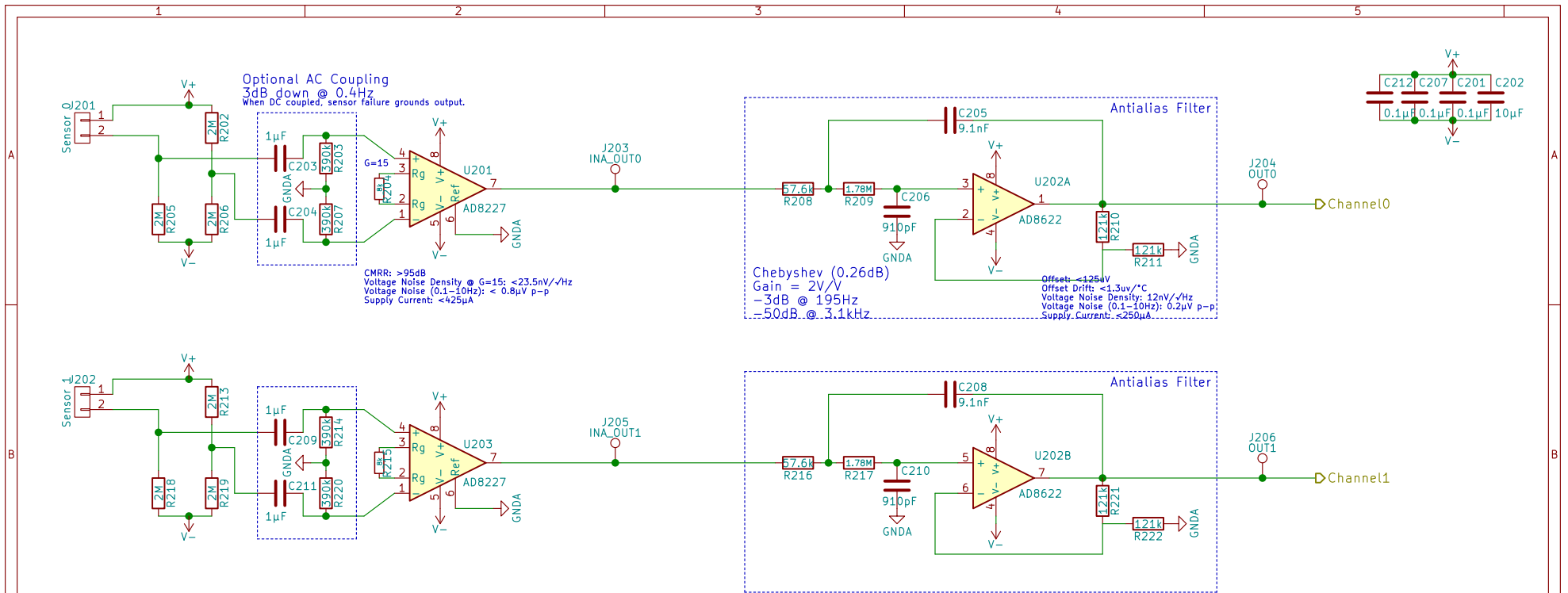
Monadnock Systems

Sheet: /  
File: bmi-8ch.sch

**Title: Polymer Sensor Amplifier**

Size: USLetter Date: 2017-03-26  
KiCad E.D.A. kicad 4.0.6

Rev: AB  
Id: 1/5



**Notes:**

Designed for  $\pm V_{batt}/2$  Output (INA is only gain element)  
 May damage ADC if input range is  $\leq \pm V_{BATT}/2$

- R204, R213: 0.1%
- R208, R209: 1%
- R202, R205, R206 & R203, R207: Metal Foil / Thin Film (Resistor packs preferred)
- ALL C: 5%, 16V

**Assumptions:**

- (Initial) DAQ is MCC USB-1208FS (available at BMI)
- 11-bit, max 6250 S/sec for each channel; sequential
- Target Bandwidth: 195Hz
- Sampling Rate 6240 S/s
- Sensor resistance  $2M\Omega$
- Respiration motion changes sensor resistance by  $< \pm 10\%$

**Analysis Notes:**

1. Steep digital filter 0.4-175Hz
  - Respiration typically 0.25-0.33Hz
  - Narrower useful bandwidth likely, modeling needed.
2. Correct for temporal offset of sample due to sequential sampling.
3. 2x decimation for 13-bit (ENOB) and noise reduction

**Open Questions:**

1. Trimming the bridge.
  - Only makes sense w/ DC coupling
  - Bad tempo
  - Bad UX
  - Needed for significant gain
2. AC vs DC Coupling; both have advantages: AC is easier
3. Reducing R202,R203,R206,R207 to decrease Johnson noise: Probably useless.
  - Changing R202,R206 may break INAMP CMRR
4. Use chopper amps in signal path: Probably bad
  - Lower total noise for \*extremely\* small bandwidths (<5Hz?)
  - Lower offset (if DC coupled)
5. Driven shields for output: Probably useless
  - Reduce error due to leakage current
  - No analysis done to determine if this is significant
  - Current DAQ isn't likely to benefit

**Problems:**

- USB-1208FS has fixed single-ended range of  $\pm 10V$
- Reduces ENOB to 11 if running on 5V supply
- Drop in upgrade to USB-1608FS (16bit and variable range)
- Can be substantially mitigated initially by running on 18V via two 9V batteries.

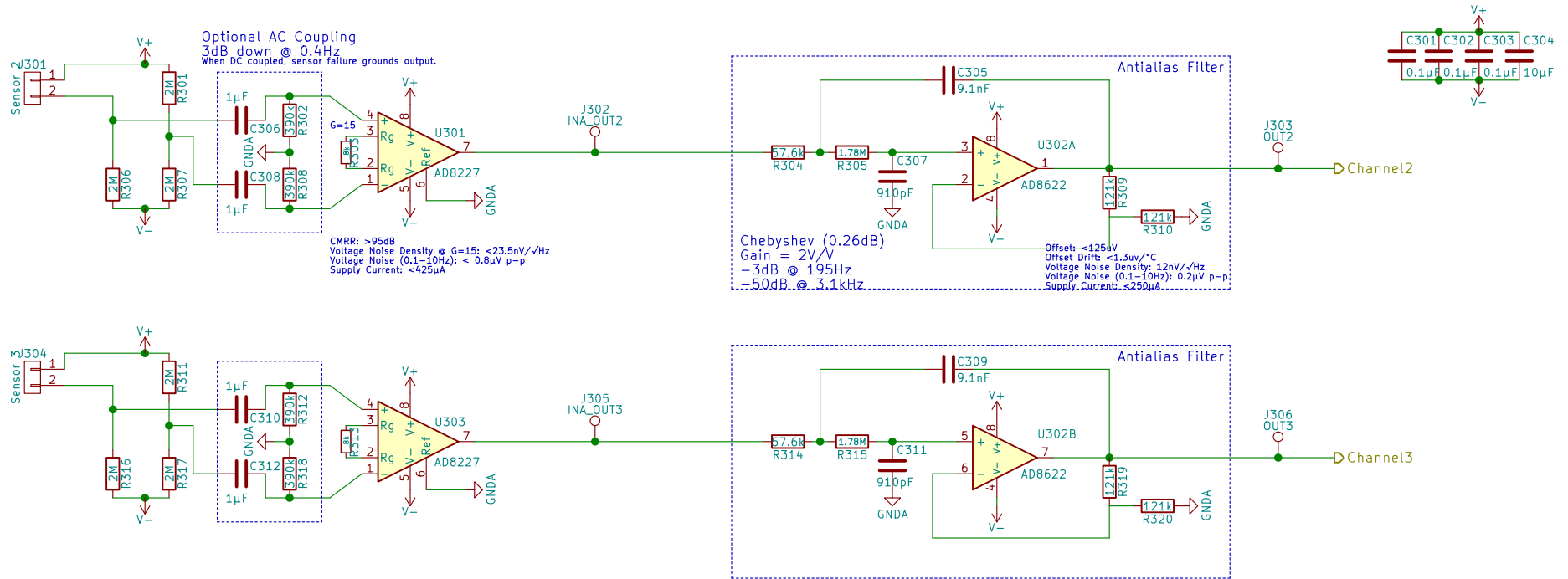
**Monadnock Systems**

Sheet: /channel0-1/  
 File: channel0.sch

**Title: Input Channel 0 & 1**

Size: USLetter    Date: 2017-03-26  
 KiCad E.D.A.    kicad 4.0.6

Rev: AB  
 Id: 2/5



Notes:  
Designed for  $\pm V_{batt}/2$  Output (INA is only gain element)  
May damage ADC if input range is  $\leq \pm V_{BATT}/2$

R204, R213: 0.1%  
R208, R209: 1%  
R202, R205, R206 & R203, R207: Metal Foil / Thin Film (Resistor packs preferred)  
ALL C: 5%, 16V

Assumptions:  
- (Initial) DAQ is MCC USB-1208FS (available at BMI)  
- 11-bit, max 6250 S/sec for each channel; sequential  
- Target Bandwidth: 195Hz  
- Sampling Rate 6240 S/s  
- Sensor resistance  $2M\Omega$   
- Respiration motion changes sensor resistance by  $< \pm 10\%$

- Open Questions:
- Trimming the bridge.
    - Only makes sense w/ DC coupling
    - Bad tempo
    - Bad UX
    - Needed for significant gain
  - AC vs DC Coupling; both have advantages: AC is easier
  - Reducing R202,R203,R206,R207 to decrease Johnson noise: Probably useless.
    - Changing R202,R206 may break INAMP CMRR
  - Use chopper amps in signal path: Probably bad
    - Lower total noise for \*extremely\* small bandwidths (<5Hz?)
    - Lower offset (if DC coupled)
  - Driven shields for output: Probably useless
    - Reduce error due to leakage current
    - No analysis done to determine if this is significant
    - Current DAQ isn't likely to benefit
- Problems:
- USB-1208FS has fixed single-ended range of  $\pm 10V$ 
    - Reduces ENOB to 11 if running on 5V supply
    - Drop in upgrade to USB-1608FS (16bit and variable range)
    - Can be substantially mitigated initially by running on 18V via two 9V batteries.

- Analysis Notes:
- Steep digital filter 0.4–175Hz
    - Respiration typically 0.25–0.33Hz
    - Narrower useful bandwidth likely, modeling needed.
  - Correct for temporal offset of sample due to sequential sampling.
  - 2x decimation for 13-bit (ENOB) and noise reduction

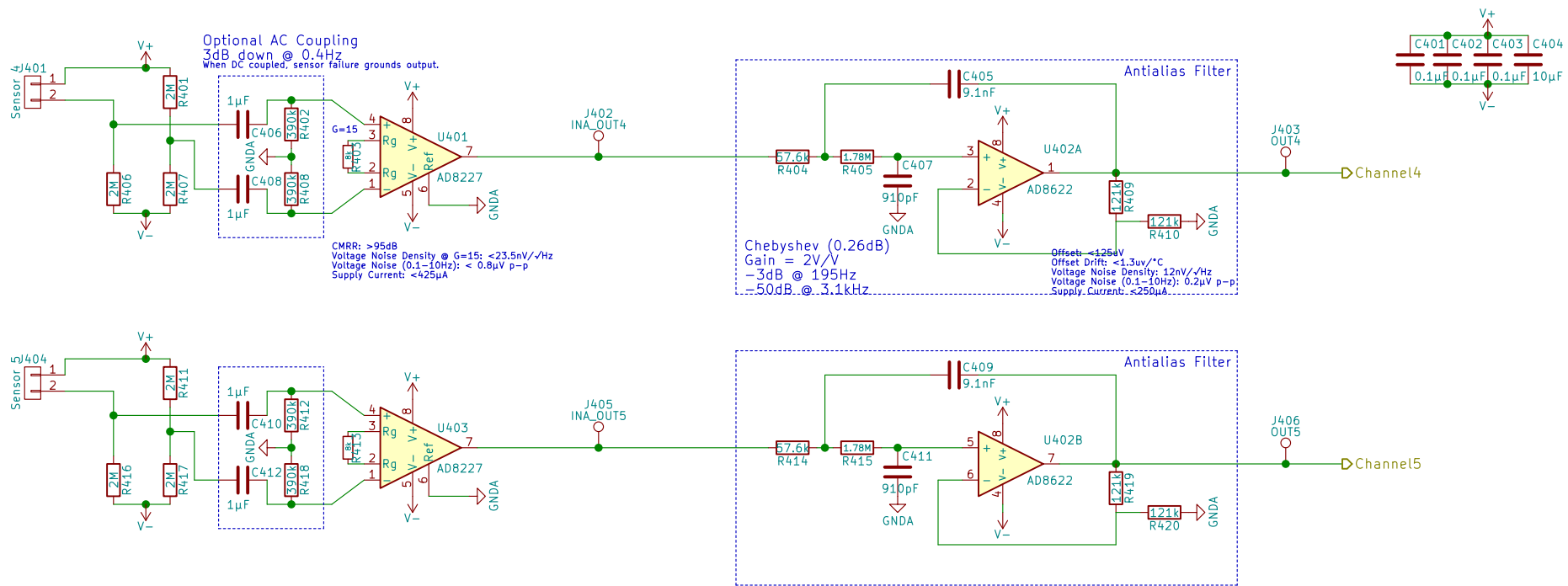
**Monadnock Systems**

Sheet: /channel2-3/  
File: channel2.sch

**Title: Input Channel 0 & 1**

Size: USLetter Date: 2017-03-26  
KiCad E.D.A. kicad 4.0.6

Rev: AB  
Id: 3/5



Notes:  
 Designed for  $\pm V_{batt}/2$  Output (INA is only gain element)  
 May damage ADC if input range is  $\leq \pm V_{BATT}/2$

R204, R213: 0.1%  
 R208, R209: 1%  
 R202, R205, R206 & R203, R207: Metal Foil / Thin Film (Resistor packs preferred)  
 ALL C: 5%, 16V

Assumptions:  
 - (Initial) DAQ is MCC USB-1208FS (available at BMI)  
 - 11-bit, max 6250 S/sec for each channel; sequential  
 - Target Bandwidth: 195Hz  
 - Sampling Rate 6240 S/s  
 - Sensor resistance  $2M\Omega$   
 - Respiration motion changes sensor resistance by  $< \pm 10\%$

- Open Questions:
- Trimming the bridge.
    - Only makes sense w/ DC coupling
    - Bad tempo
    - Bad UX
    - Needed for significant gain
  - AC vs DC Coupling; both have advantages: AC is easier
  - Reducing R202, R203, R206, R207 to decrease Johnson noise: Probably useless.
    - Changing R202, R206 may break INAMP CMRR
  - Use chopper amps in signal path: Probably bad
    - Lower total noise for \*extremely\* small bandwidths (<5Hz?)
    - Lower offset (if DC coupled)
  - Driven shields for output: Probably useless
    - Reduce error due to leakage current
    - No analysis done to determine if this is significant
    - Current DAQ isn't likely to benefit

- Problems:
- USB-1208FS has fixed single-ended range of  $\pm 10V$ 
    - Reduces ENOB to 11 if running on 5V supply
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- Analysis Notes:
- Steep digital filter 0.4-175Hz
    - Respiration typically 0.25-0.33Hz
    - Narrower useful bandwidth likely, modeling needed.
  - Correct for temporal offset of sample due to sequential sampling.
  - 2x decimation for 13-bit (ENOB) and noise reduction

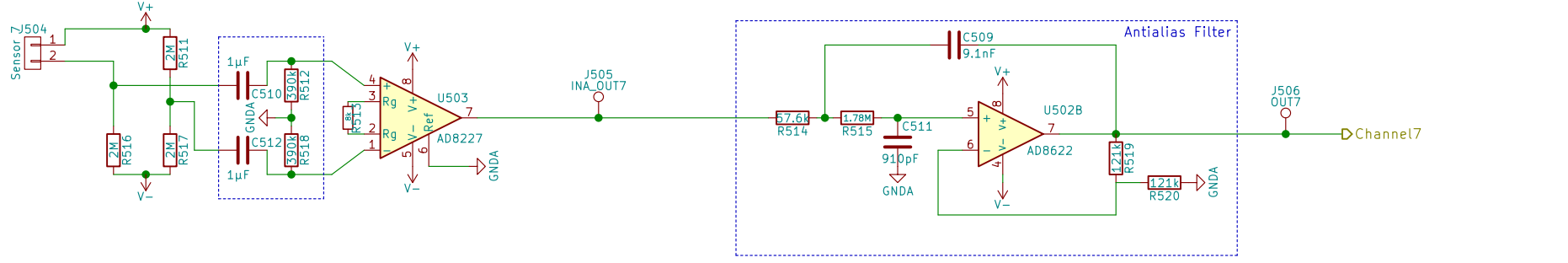
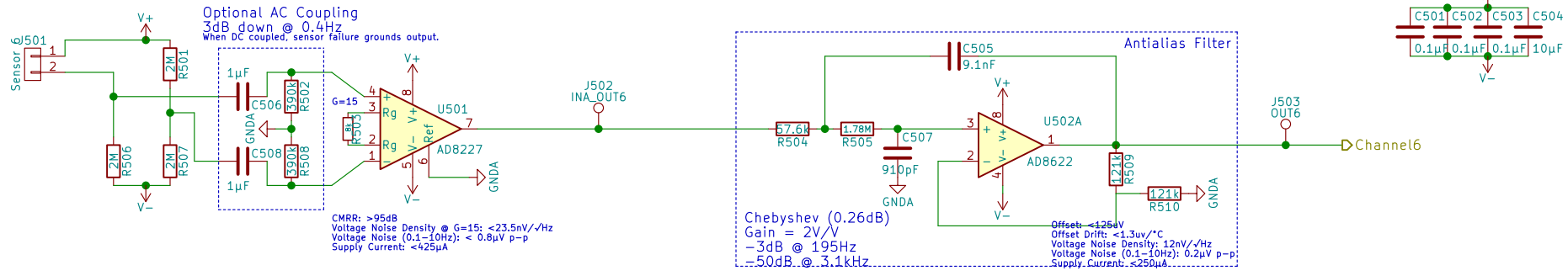
**Monadnock Systems**

Sheet: /channel4-5/  
 File: channel4.sch

**Title: Input Channel 0 & 1**

Size: USLetter Date: 2017-03-26  
 KiCad E.D.A. kicad 4.0.6

Rev: AB  
 Id: 4/5



Notes:  
Designed for  $\pm V_{batt}/2$  Output (INA is only gain element)  
May damage ADC if input range is  $\leq \pm V_{BATT}/2$

- R204, R213: 0.1%
- R208, R209: 1%
- R202, R205, R206 & R203, R207: Metal Foil / Thin Film (Resistor packs preferred)
- ALL C: 5%, 16V

- Open Questions:
1. Trimming the bridge.
    - Only makes sense w/ DC coupling
    - Bad tempo
    - Bad UX
    - Needed for significant gain
  2. AC vs DC Coupling; both have advantages: AC is easier
  3. Reducing R202,R203,R206,R207 to decrease Johnson noise: Probably useless.
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  4. Use chopper amps in signal path: Probably bad
    - Lower total noise for \*extremely\* small bandwidths (<5Hz?)
    - Lower offset (if DC coupled)
  5. Driven shields for output: Probably useless
    - Reduce error due to leakage current
    - No analysis done to determine if this is significant
    - Current DAQ isn't likely to benefit

- Problems:
- USB-1208FS has fixed single-ended range of  $\pm 10V$
  - Reduces ENOB to 11 if running on 5V supply
  - Drop in upgrade to USB-1608FS (16bit and variable range)
  - Can be substantially mitigated initially by running on 18V via two 9V batteries.

- Assumptions:
- (Initial) DAQ is MCC USB-1208FS (available at BMI)
  - 11-bit, max 6250 S/sec for each channel; sequential
  - Target Bandwidth: 195Hz
  - Sampling Rate 6240 S/s
  - Sensor resistance  $2M\Omega$
  - Respiration motion changes sensor resistance by  $< \pm 10\%$

- Analysis Notes:
1. Steep digital filter 0.4–175Hz
    - Respiration typically 0.25–0.33Hz
    - Narrower useful bandwidth likely, modeling needed.
  2. Correct for temporal offset of sample due to sequential sampling.
  3. 2x decimation for 13-bit (ENOB) and noise reduction

<b>Monadnock Systems</b>	
Sheet: /channel6-7/ File: channel6.sch	
<b>Title: Input Channel 0 &amp; 1</b>	
Size: USLetter	Date: 2017-03-26
KiCad E.D.A. kicad 4.0.6	Rev: AB Id: 5/5